DISPERSION MEASUREMENT USING A TWO-COLOUR SIGNAL WITH BER/EYE OPENING RESPONSE

Field of the Invention

The invention resides in the field of optical telecommunications networks, and is directed in particular to dispersion measurement in optical networks.

Background of the Invention

In optical transmission systems, the user traffic is carried by one or more channels traveling between a transmitter and a receiver in optical format. The receiver task is to convert the optical signal back into an electrical format and to extract the user signal. A channel is defined as a carrier wavelength modulated with user signal. Ideally, a light pulse (representing a digital "1") is a surge of light of a certain power at wavelength λ_0; in fact, the pulse of light has a certain "width" comprised of a small range of wavelengths about the central wavelength, so that a channel has a certain width as shown in Figure 1A.

The optical fibers used as the transmission medium in most optical communication links and most optical components (optical amplifiers, filters), are dispersive, that is, different wavelengths of light travel at slightly different phase velocities $v_{ph} = \omega/k = c/n(\lambda)$, where c is the vacuum speed of light. The propagation characteristics of each wavelength depend on the effective mode index $n(\lambda)$, or the effective propagation parameter $k = 2\pi n(\lambda)/\lambda$. The mode index changes with wavelength, polarization and mode profile, due to material dispersion and due to the waveguide dispersion of the confined mode. The effective mode index $n(\lambda)$ shows a non-linear wavelength dependence over an extended spectral domain. As a result, not only the phase velocity, but also the group velocity $v_g = \partial \omega / \partial k = c/[n - \lambda(dn/d\lambda)]$ changes with wavelength. The group velocity is the speed at which non-uniformities in the field intensity, such as an

information-carrying modulated pulse train, move through the medium. However, an initially short pulse requires some spectral width as dictated by the fundamental property of Fourier transforms. As a result, the wavelength-dependence of the group velocity tends to broaden the pulse as it propagates

5   through the fiber, because different spectral components of the pulse travel at different velocities.

This wavelength-dependence of the propagation parameter and consequently of the group velocity is termed chromatic dispersion CD, or intra-modal dispersion. Figure 1B shows a signal '100101' at the input of an optical

10   link, and Figure 1C illustrates how the light pulses representing the '1' 'widen' as the signal travels down the fiber. As a result, the pulse energy of symbols "1" spreads into the neighboring symbols "0" (ISI or intersymbol interference), so that the receiver could interpret the signal correctly as '100101', or erroneously as '100111'.

15   It is evident that reconstructing the user signal from the received optical pulses can pose problems, especially in WDM (wavelength division multiplexed) systems, where a plurality of channels travels over the same link.

The chromatic dispersion parameter $D(\lambda)$ is defined as:

20   $$D(\lambda) = \frac{\partial \tau}{\partial \lambda} \cdot \frac{1}{L} \qquad\qquad\qquad \text{EQ1}$$

where $\partial \tau$ is the differential group delay (DGD) of two pulses, i.e. the variation of the travel time (in picoseconds) from the transmitter to the point of measurement, $\partial \lambda$ is the differential spectral separation of the two carrier

25   wavelengths (in nanometers) and L is the length of the fiber (in kilometers) over which the dispersion is measured. The dispersion is measured in ps/(nm km). For example, for every km of fiber traveled through, two pulses with a 1 nm initial separation of wavelengths will experience a differential group delay of 1 ps, if the dispersion of the fiber is 1 ps/(nm km). Similarly, the two outlying spectral

30   components of a 10Gb/s pulse with a 0.2 nm spectral width, will widen by a

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whole bit period (100ps) after some propagation distance, and will then cause bit errors by spreading the pulse energy into the neighboring symbol.

Since the dispersion parameter D is wavelength-dependent, it may be approximated in the spectral domain around a center wavelength λ_c by:

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$$D(\lambda) = D(\lambda_c) + S(\lambda_c)(\lambda - \lambda_c) + 1/2C(\lambda_c)(\lambda - \lambda_c)^2 \qquad \text{EQ2}$$

where $S(\lambda_c)$ and $C(\lambda_c)$ are respectively the dispersion slope and curvature at λ_c. The dispersion slope is given by:

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$$S = \partial D / \partial \lambda \qquad \text{EQ3}$$

If we assume a linear dispersion slope, the slope can be expressed as the ratio of change in the dispersion to the change in the wavelength $\Delta D / \Delta \lambda$

15 calculated with respect to a reference wavelength.

Chromatic dispersion can be corrected, or "compensated," through the use of specially designed optical components (such as fibers, Bragg gratings) inserted at given locations along the transmission path. For a comprehensive compensation, the dispersion of the compensating component (which could be packaged e.g. as a dispersion compensating module DCM) must be - $D(\lambda)$, i.e.

20 must have the same value, but opposite sign to the dispersion of the preceding transmission section.

With the data rates of optical communication systems increasing through techniques such as dense WDM (DWDM), and network reach increasing through

25 techniques known as ultra long reach (ULR), determination of chromatic dispersion of the fiber and optical components within the systems becomes increasingly important. In ULR systems, the link dispersion is preferably compensated to have an optimal non-zero value (target value) on all links. Thus, dispersion of each transmission section needs to be determined with as much

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accuracy as possible to provide accurate compensation, for achieving longer un-regenerated reach and ultimately a less expensive network.

Fiber cable manufacturers provide chromatic dispersion coefficients by wavelength windows for each fiber cable type. Also, most device specifications

5   include CD information. A simple way to determine the total dispersion over a link is to multiply the dispersion coefficient for a certain type of fiber by the fiber length in km and to add to this the specified dispersion of the optical components connected in the respective link.

This method is often used in current point-to-point networks, where each

10 span/link is provisioned based on estimated data, using in addition generous engineering margins to ensure that the span/link will successfully carry the traffic over the specified distance. This is clearly not the best way of using network resources.

In addition, in many cases the fiber type is not known; there are no reliable methods to detect the type of the fiber buried in early days of the optical

15 networking. Also, this method assumes a uniform dispersion along the entire fiber cable length, which is not generally true. While this assumption can be used in systems with a small channel-count and short links, it is not satisfactory for wavelength switched DWDM (dense WDM) systems.

A more accurate value of dispersion is evidently obtained by measuring

20 the dispersion. Chromatic dispersion can be determined by performing time domain measurements and frequency domain measurements, as described for example by P.J Dean in "Optical Fiber Communications, Principles and Practice", published in 1985 by Prentice-Hall International, Inc, London, pages

25 196-202.

However, current dispersion measurement methods can not be readily used in wavelength switched (agile) networks, for at least the following reasons.

a) The current networks have a point-to-point architecture that uses span equalization, so that the existing dispersion measuring methods can provide

30 accurate dispersion measurements for a span, which is a relatively short lengths of fiber (100-150km) and does not include optical amplifiers.

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In wavelength switched networks (or agile network) a channel travels for much longer distances in optical format (without regeneration) than in point-to-point networks, passing through a plurality of optical amplifiers and intermediate nodes (switching nodes and/or optical add/drop nodes). Also, in optically

5   amplified end-to-end links, amplified spontaneous emission (ASE) reduces the received signal-to-noise ratio and may introduce severe measurement errors.

b) Some traditional dispersion measurement methods require bi-directional transmission. An optical amplifier however, contains optical isolators prohibiting bidirectional transmission of probe or reference signals.

10   c) In agile networks, end-to-end physical routes (paths) are dynamically set-up and removed arbitrarily (based on users' requests) without interruption of the co-propagating traffic. Agility requires accurate knowledge of the link parameters, which include end-to-end (link) dispersion, since matching an end-to-end path to a connection request is based, among other rules, on individual

15   link/path performance. The chances of setting-up a connection along a path increase (and the time-to-service decreases) if the selection process uses accurate path performance parameters.

d) As well, the current dispersion measurement methods may not be able to cope with the bandwidth-limiting effects introduced by spectral filters in end-to

20   end links.

There is a need to provide a method for measuring dispersion of an end-to-end link of an optical network, that is reliable and inexpensive.

Summary of the invention

25   It is an object of the present invention to provide a dispersion measurement method and arrangement that alleviates totally or in part the drawbacks of the prior art dispersion measurement methods.

It is another object of the invention to provide a method for measuring dispersion in D/WDM networks that is reliable, accurate and inexpensive.

Another object of the invention is to provide a dispersion measurement card that can be inserted at all optical amplifiers and switching nodes of a communication network to provide an accurate measurement of the dispersion.

Accordingly, the invention provides a method for measuring dispersion of

5   an optical link of an optical network comprising: generating at a transmit end of a link under test LUT, a two-color signal of a first and a second wavelength, each modulated with a digital signal, and transmitting same over the LUT; changing the second wavelength with respect to the first wavelength with a detuning value to impose a known delay between the digital signal carried by the first

10   wavelength and the digital signal carried by the second wavelength; and measuring the BER of the two-color signal for a plurality of detuning values to obtain a BER response.

According to another aspect of the invention, there is provided a dispersion measurement apparatus comprising: a transmitter unit for generating

15   a two-color signal and transmitting same over a link under test; a receiver for detecting a combined electrical signal from the two-color optical signal and measuring the BER of the combined electrical signal; and a dispersion calculating unit for determining the dispersion of the link under test.

Since an end-to-end connection is determined in an agile network after

20   equipment deployment, wavelength switched systems may use measured data, such as link dispersion information, to independently engineer each end-to-end path. Experimental evidence shows that use of measured as opposed to estimated data results in a much better path-connection matching, and could increase the deployed system reach by 50%.

25   The invention allows to accurately select the fixed dispersion compensating modules DCMs and to adjust the tunable DCMs such that the network reach is optimized for each connection. Thus, the fixed DCMs may be selected in an open loop. Semi-automated closed loop testing can be performed where software selected DCMs are replaced until the target is achieved. Full

30   closed loop adjustment of tunable DCMs (when available) to the link target value may be performed at the switching nodes. Thus, the invention enables auto-

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optimization of the network since it uses for dispersion measurement the transmission equipment that is already in place.

Another advantage is that accurate measurement of dispersion for each channel along each fiber link increases the likelihood of setting-up a connection

5   along a selected path, resulting in less connection set-up time and thus a faster and less expensive service to the network users. Accurate values for the link dispersion may also be used in selecting the power targets for each wavelength, to increase the reach of selected channels based on users' demand.

Also, the method according to the invention can be used in the presence

10   of data traffic in the adjacent channels. It blends in naturally, because the power targets, modulation formats and test signal bandwidth are identical to, or do not exceed the parameter range designed for data carrying signals in the system.

To summarize, using measured dispersion data as in the present invention results in important network cost savings.

Brief Description of the Drawings

The foregoing and other objects, features and advantages of the invention will be apparent from the following more particular description of the preferred embodiments, as illustrated in the appended drawings, where:

20   Figures 1A-1C show chromatic dispersion, where Figure 1A shows the spectral width of a pulse of light; Figure 1B shows the shape of a data signal at the input to a dispersive fiber link and Figure 1C shows the same data at the output of the link;

Figure 2 is a block diagram of a transport link connected in a dispersion

25   measurement arrangement according to an embodiment of the invention;

Figure 3A shows a plurality of eye diagrams for the two-colour signal obtained from simulations for six detuning values;

Figure 3B is a BER versus frequency graph illustrating the frequencies regimes corresponding to the eye diagrams of Figure 3A;

Figure 4A is a simulated eye diagram for a two-colour NRZ encoded data signal used for dispersion measurement for a mT_B and a $(m+1/2)T_B$ differential group delay;

Figure 4B shows a simulated eye diagram of a two-colour RZ encoded

5 data signal used for dispersion measurement for a mT_B and a $(m+1/2)T_B$ differential group delay;

Figure 5A is a BER-frequency graph (decimal and exponential versions) for an on-grid L-band scan, over a link with a total dispersion DL= 25 ps/nm and using a 1:4 power ratio of the two input wavelengths;

10 **Figure 5B** shows the group delay profile deduced from the graphs of Figure 5A;

Figure 5C shows the dispersion profile deduced from the graphs of Figure 5B;

Figure 6 is a block diagram of a transport link connected in a dispersion

15 measurement arrangement according to another embodiment of the invention;

Figure 7A shows the BER v. frequency graph generated using a variable ratio between the launch powers of the two input wavelengths; and

Figure 7B shows BER responses for various launch power ratios extracted from the graph of Figure 7A.

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Detailed Description of the Preferred Embodiments

As discussed in the background section, Figures 1A-1C show the chromatic dispersion phenomenon. As seen in Figure 1A a pulse of light has a

25 spectral width, which includes a small range of wavelengths on both sides of the central wavelength λ_0. Figure 1B shows the shape of a data signal '100101' at the input to a dispersive fiber link, and Figure 1C shows the same data at the output of the link. As indicated above, the pulses broaden as they travel along a dispersive link; the ISI (inter-symbol interference) impacts the quality of reception

30 at the receiver.

Figure 2 is a block diagram of an end-to-end link between a transmit and a receive node of a WDM network, showing a dispersion measuring arrangement according to an embodiment of the invention. This Figure shows dispersion measurement for forward (West to East) traffic; it is to be noted that similar

5   operations and equipment may be used for measuring dispersion on the reverse links.

An optical transmitter unit 2 located at the transmit node generates a two-colour optical signal 4. Transmitter unit 2 comprises a first optical source 1 for generating a first carrier wavelength λ_1 and a second optical source 1' for

10   generating a second carrier wavelength λ_2. Sources 1, 1' may be CW laser diodes or the like. The two wavelengths are combined in a modulator 3 so that the bit patterns on both carrier fields are phase-synchronized. The combiner 12 can be any such well known device connected at the input of the modulator 3. The modulator can be a Mach-Zehnder; the modulating signal source is shown

15   at 5. It is to be noted that modulation signal source 5 and modulator 3 may realize any modulation format, amplitude, phase, frequency-shift keying (ASK, PSK, FSK) or any combinations of these.

LUT 7 symbolically represents the link under test. Link 7 includes the fiber 6 and all optical components 8 between the transmitter unit 2 and a far-end

20   receiver 9. Block 8 may include the optical components of the add structure at the transmit node, drop structure at the receive node and the optical components along fiber 6 connecting the two nodes. In general, these are optical active devices, such as optical amplifiers, tunable filters, wavelength selectors/blockers, and optical passive components, such as splices, splitters, connectors, etc. and

25   the transport medium (the fiber).

A single light detector 9 at the output of LUT 7 recovers the electrical signals carried by the two wavelengths. The optical detector 9 may be a broadband receiver (i.e. is not wavelength-specific), such as a PIN photodetector as well known in the art. The detected photocurrent is then low-

30   pass filtered, as shown at 11. Alternatively, a modulated broadband source

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could be used with a tunable dual wavelength filter at the receiver. Other variants can also be envisaged.

The detected signal is provided to a dispersion calculating block **13** described next in connection with Figures 3A, 3B, 4A, 4B, and 5A, 5B, 5C.

5   Optionally, the eye diagram of the two-colour signal can be viewed, as shown at **15**.

It is to be noted that transmitters **1** and **1'** and receiver **9** could be equipment physically connected in the network and that the dispersion measurement may be performed on-line or off-line. In general, agile networks

10   have at each/some switching nodes a number of idle transmitters and receivers, ready to be allocated to a new connection or just released from a removed connection. Thus, on-line dispersion measurement could be performed using two free transmitters at one end of the link and a free receiver at the other end. It is also to be noted that the drop structure of such agile

15   networks may use a tunable filter in front of each receiver to select the channel assigned to that receiver for a certain connection. For dispersion measurement, the tunable filter is excluded from LUT **7**.

First, a BER measuring unit shown at **20** in Figure 2 measures the BER of the two-colour signal using any known methods. Figure 3A shows a plurality

20   of eye diagrams of the two-colour signal for six detuning values, and Figure 3B is a BER versus frequency graph illustrating the frequencies regimes corresponding to the eye diagrams of Figure 3A.

The diagrams were obtained using two CW lasers **1**, **1'** combined with a 3-dB coupler at the input of modulator **3**. Laser **1** emits $\lambda 1$ with a frequency of

25   191.583 THz (L-band) at a launch power of 1 mW. Laser **1'** emits wavelength $\lambda 2$ at a launch power of 0.25 mW, with the frequency increasing from 191.583 THz in increments of 50 GHz. Both lasers have a 10 MHz line width. Signal generator **5** generates a 10-Gb/s NRZ signal (T_B=100 ps), which is modulated onto the combined fields by modulator **3**. After linear propagation through the

30   500-km LUT **7** with a residual dispersion of 0.05 ps/(nm km) and a zero dispersion slope, receiver **9** detects the superimposed fields and the eye of the

two-colour signal is evaluated. The receiver bandwidth is 7 GHz. The BER response and the eye diagrams are recorded as a function of the wavelength $\lambda 2$ of laser 1'.

Three distinct frequency regimes can be identified on the BER graph as

5   follows:

1) Around zero detuning, the eye exhibits large power fluctuations on the upper traces, which lead to a significant eye closure, as shown by eye **a**. The superposition of the two laser fields (10 MHz line width) produces amplitude fluctuations within the receiver bandwidth (7 GHz). As expected, the fluctuations

10   disappear and the eye opens up when the detuning is greater than the detector bandwidth. Therefore, the narrow 7-GHz regime may be called *dual-signal-beat-noise regime.*

2) Between 50 GHz and 600 GHz the eye is wide open as shown by eye diagrams **b**, **c** and **d**. In this regime the dual signal beat noise is eliminated, and

15   the differential group delay is still within a bit period T_B. Therefore the received patterns are correlated. The intensities of the two signals add coherently, but their fields add incoherently, thus keeping the eye open. Therefore, this regime may be called the *correlated-pattern regime.*

3) For a detuning value larger than 800 GHz, the BER becomes an

20   oscillating function of the detuning, shown by eyes **e** and **f**. The eye opening varies with the relative group delay of two uncorrelated patterns; therefore this regime may be called the *uncorrelated-pattern regime.* The eye closes due to the twin-wavelength inter-symbol interference (ISI) in the two-colour signal when the differential group delay becomes close to integer values of a bit period

25   $\tau=mT_B$. The eye opens for a half-period superposition of the two signals $\tau=(m+1/2)T_B$. This regime is better seen in Figures 4A and 4B.

Figure 4A shows a simulated eye diagram of a two-colour NRZ encoded data signal used for dispersion measurement, and Figure 4B shows a similar simulation for a RZ data signal. For each of Figures 4A and 4B, simulation **a**

30   shows the eyes for a mT_B differential group delay, and simulation **b** shows the eyes for a $(m+1/2)T_B$ differential group delay, the two signals having the same bit

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period T_B, but different powers. The upper part of each graph shows the eye of the first data signal $E\lambda_1$, the middle part shows the second data signal $E\lambda_2$, while the lower part shows the eye of the two-color signal denoted with $E\lambda_1, \lambda_2$.

As seen in Figures 4A and 4B, if the power ratio of the two wavelengths

5   is chosen such that the weaker field modulates the eye of the stronger field, a periodic eye closure is obtained. Due to the periodically changing statistical weight of various power levels in the NRZ modulation format (between $p=1/2$ for the two levels at the center of the bit period, and $p=1/4$ for the four distinct levels near the bit period boundaries), the BER of the combined eye is higher

10   whenever the DGD (differential group delay) is multiples of bit period ($p=1/4$), and lower in-between ($p=1/8$), even though the geometric noise-free eye opening does not change for NRZ signals. The maximum BER is obtained for detuning values that produce a $\tau=mT_B$ and the minimum BER is obtained for detuning that produce $\tau=(m+1/2)T_B$, where m is an integer value.

15   It should be noted that for an RZ signal, shown in Figure 4B, a periodic geometric eye opening is actually observed, which enhances the undulation of the BER for various DGDs.

In both cases, the BER changes periodically for increasing frequency offsets, with a period equal to the bit period group delay.

20   A numerical experiment is provided next for illustrating the dispersion measurement. Figure 5A shows a BER versus frequency graph for the L band, using one laser with fixed wavelength λ_1 of 1570.0 nm (190.95 THz) and a tunable laser of wavelength λ_2 that is tuned in steps of 50 GHz (0.42 nm) over 90 channels (4.5 THz) to 1607.9 nm (186.45 THz). It is apparent that the

25   succession of maximums-minimums of eye closures (or openings) result in an undulating BER response. In Fig. 5A, the first BER peak appears for a relative group delay of $\tau_2 = 2\ T_B$. The next peaks are due to group delays of $\tau_m = m\ T_B$.

The periodic eye closure may be expressed as in EQ4:

30    $\text{BER}(\tau) = \text{BER}(\tau + T_B)$ EQ4

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The magnitude of the relative group delay can therefore be inferred from the undulated BER response as a function of the wavelength detuning. Figure 5B shows the group delay profile $\tau(\lambda)$ deduced from the graphs of Figure 5A.

Returning now to Figure 2, the BER measuring unit **20** of dispersion calculating block **13** provides a BER response based on BER measurements for various detuning. BER measurement unit **20** may be for example a software module, and the BER response refers in this specification to a BER graph and/or its key features (minima and maxima in the uncorrelated pattern regime, correlated pattern regime). The BER response is preferably stored in unit **14**, in the form of a BER graph, or/and its key features.

The BER response may be used to give feedback to wavelength and power ratio adjustments for optimizing the dispersion measurement accuracy, range and speed. It is possible for example to select a BER maximum in a region of interest, and to take more measurements for certain frequencies in the vicinity of the maximum.

Block **13** also includes group delay profile calculating unit **21**, which calculates $\tau(\lambda)$ from the BER response. Unit **21** may again be a software module, which determines the relative group delay as a function of wavelength, using the BER response measured by unit **20**.

Figure 5C shows the dispersion profile versus wavelength $D(\lambda)$, calculated as in EQ1 from a fit for the $\tau(\lambda)$ dependency of Figure 5B. A second order polynomial fit for the $\tau(\lambda)$ dependency can be determined from Figure 5B. Figure 2 shows generically block **22** that determines a, b and c from $\tau(\lambda)$ graph **20**. Block **20** can be again a software module:

$$\tau(\lambda) = a + b(\lambda - \lambda_{ref}) + c(\lambda - \lambda_{ref})^2 \qquad \text{EQ5}$$

Arbitrarily choosing a reference wavelength of λ_{ref} = 1569.99 nm, the resulting parameters are a=-3.0182 ps, b = 25.178 ps/nm, and c = -0.0029 ps/nm^2 after a 4% error due to polarization mode dispersion (PMD) has been added to the group delay.

Alternatively, the three or five-term Sellmeier equation is used for curve fitting of $\tau(\lambda)$, as discussed in e.g. the book "Fiber Optic Test and Measurement" edited by Dennis Derickson (Prentice Hall, New Jersey, 1998), pages 479-487.

5   The term "fit function" is used for defining the second order polynomial, the three or five-term Sellmeier equation, or other alternative means expressing the group delay profile shown in Figure 5B.

Dispersion measurement unit **13** also includes a block **23**, which calculates dispersion D and dispersion slope S using EQ6 and the definitions of D and S given by EQ1, and EQ 2, respectively. For a particular example where

10   L=500 km:

$$D = \frac{1}{L}[b + 2c(\lambda - \lambda_{ref})] = 0.050\frac{ps}{nm \cdot km} - (\lambda - \lambda_{ref}) \cdot 1.16 \cdot 10^{-5}\frac{ps}{nm^2 km}$$

$$S = \frac{2c}{L} = -1.16 \cdot 10^{-5}\frac{ps}{nm^2 km} \qquad\qquad\qquad EQ6$$

The input D value used in the simulation was 0.05 ps/(nm km) with no slope. The extracted D shows good agreement with the input D.

15   Tables with group delay values extracted from the BER-frequency graphs, and also including the grid wavelengths or interpolated wavelengths closest to the BER peaks can be provided using this method, so that performance of each wavelength on a certain link is known in advance. As indicated above, the data may be for example stored in a memory **14** for use by dispersion measurement

20   unit **13**. This data may be used for tuning the link dispersion to the target value during SLAT (system line-up and test), for determining the value of the fixed dispersion compensating modules inserted at the optical amplification sites, etc. The measured dispersion data can also be used in agile networks for mapping a wavelength to a connection during path selection process.

25   Basically, a two-colour scheme takes advantage of a stronger distortion effect by probing the chromatic dispersion with a larger bandwidth $\Delta\lambda$ *(0.42 nm) × (number of channels)*. As shown below, the measurement of inter-band group delay can therefore be approximately 100 times more sensitive

as compared to a dispersion measurement scheme that uses a limited single-channel bandwidth

$$\frac{\Delta\lambda_{band}}{\delta\lambda_{channel}} = number\ of\ channels \cong 100$$

Figure 6 shows a transmitter unit 20 comprising two transceivers 27 and 27', operating in a regenerator mode. Namely, the transceivers receive the same input signal on a unique wavelength λ_{source}, recover the data signal carried by the λ_{source}, and modulate it over a respective different carrier wavelength λ_1 and λ_2. The two wavelengths so modulated are combined in combiner 12 to give the two-colour signal 4. In this way, both signals are phase synchronized at the transmit end and have $\tau=0$.

The remainder of the arrangement is as in Figure 2.

So far, the sign of the dispersion has been guessed because no information was available whenever the LUT 7 produced a positive or negative DGD $\tau_{12} = \tau_1 - \tau_2 = \tau_{LUT}$ between reference λ_1 and probe λ_1 wavelengths. In many cases, either the sign of the dispersion is known and only the magnitude needs to be determined precisely, or the sign is not known and the magnitude needs to be compensated to zero dispersion. However, if the sign of the chromatic dispersion needs to be determined, this can be accomplished in two ways with an additional differential group delay in the system.

1) Both wavelengths are transmitted through a dispersion pre/post compensating (or enhancing) module DCM 10 as shown in Figures 2 and 7 with a known dispersion D_0L_0 and/or dispersion slope S_0L_0 at some wavelength λ_0. The result of the measurement with the DCM 10 is compared to the dispersion measurement of LUT 7 without the additional module. The DGD with the module 10 becomes $\tau_{12} = \tau_1 - \tau_2 = \tau_{LUT} + \tau_{DCM}$, which enhances or reduces the total dispersion depending on the signs of the dispersion of the LUT 7 and of the additional DCM 10. The change in DGD due to the DCM 10 is:

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$$\tau_{DCM} = D_0 L_0 (\lambda_1 - \lambda_2) + S_p L_0 [\frac{(\lambda_1 + \lambda_2)}{2} - \lambda_0](\lambda_1 - \lambda_2) \qquad \text{EQ7}$$

2) Only one wavelength PRBS is delayed optically as shown **35** in Figures 2 and 6, by a fixed value τ_0. Block **35**, shown in detail in Figure 6, comprises in input demultiplexer **12-1** and an output demultiplexer **12-2**. The de/multiplexer separate/combines, let's say wavelength $\lambda 1$, from/into the WDM signal. The unit **30'** delays the respective wavelength with τ_0.

As seen on the BER plot of Figure 3B, the remarkable dip in the BER due to the correlated pattern effect appears when the differential group delay is less than 2 bit periods, i.e. when the two PRBS intensities add coherently at $\lambda_1 \approx \lambda_2$ such that:

$$|(\lambda_1 - \lambda_2) \cdot (DL)_{LUT}| = |\tau_{LUT}| \le TB. \qquad \text{EQ8}$$

With the extra group delay τ_0 introduced in one of the two carriers, the distinguished BER dip in the correlated pattern regime appears when the two PRBS add coherently at some $\lambda_1 \neq \lambda_2$, i.e. when the BER is minimized by:

$$|(\lambda_1 - \lambda_2)(DL)_{LUT} + \tau_0| = |\tau_{LUT} + \tau_0| \le T_B, \qquad \text{EQ9}$$

which implies that:

$$-T_B - \tau_0 \le \tau_{LUT} \le T_B - \tau_0. \qquad \text{EQ10}$$

The sign of the τ_{LUT} can now be determined from the sign of τ_0.

Since in the embodiment of Figure 6, the two-color signal is obtained by combining two optical signals generated with two different transceivers, it is possible to delay one of the signals with τ_0 at the transmitter, as shown by the delay block **30**. In this case, the delay can be imposed on the respective signal in optical or electrical format.

In fact, a single fixed wavelength setting $\lambda_1 \neq \lambda_2$ is sufficient to determine the magnitude and sign of the LUT differential group delay in each above methods 1) and 2) if the extra group delay τ_{DCM} or τ_0 is not fixed, but can be tuned to minimize the BER in the correlated pattern regime which is observed at

5   zero differential group delay.

As indicated in connection with Figures 4A and 4B, the BER response is very sensitive to power and noise variations. In particular, the ratio of the powers used in the two wavelength detection scheme can be optimized for each modulation format (e.g. RZ or NRZ), filter bandwidth and eye distortion. Figure

10   7A shows a typical BER v. frequency response for a 0.19 ratio between the launch powers of the two wavelengths.

It has been noted that a variation in the BER peak values does not affect the measurement if this variation is smaller than the total minimum-to-maximum BER variation. Figure 7B shows a BER v. power ratio graph corresponding to

15   the graphs of Figure 7A. The maximum-to-minimum dynamic BER range (A) shown in the graph is compared to the dynamic range of BER peaks (B). The ratio A/B (for linear A and B) is the dynamic range left for the peak detection. In case of a small perturbation of the eye with the second signal (low power ratios, near 0.1), the BER peak values scatter too much. Towards larger power ratios,

20   near 0.5, the BER response smoothens out and the undulation disappears faster than the peak variations. The optimum power ratio for the simulated 500 km 10 GB/s NRZ transmission link is near $P(\lambda_1)/P(\lambda_2) = 0.2$, yielding a dynamic reserve of $(A/B)_{dB} = 13.8$ dB.

The optimum power ratio and dynamic reserve depends on the particular

25   modulation format, dispersion map, nonlinear distortion and optical-to-noise ratio (OSNR). These parameters change the eye shape and eye opening to which the detected BER is very sensitive. Furthermore, a fast dispersion measurement requires a higher BER to reduce the sampling time at each detuning of the wavelength. This condition also changes the desired power ratio. The purpose

30   of the previous analysis was to show that an optimum ratio actually exists and that a large dynamic reserve can be achieved for a likely dispersion

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measurement scenario. It is also possible to speed-up the measurement if the number of errors in the link is increased.

5   It has been evaluated that the accuracy of the two-colour dispersion measurement method is better than 1%. The range of dispersion measurement is 5 ps/nm < DL < 230 ps/nm for a 10 Gb/s NRZ transmitter/receiver, 35 nm total bandwidth and 50 GHz channel spacing.

The clock synchronization of the two signals can also be achieved using a regenerator-assisted signal duplication as shown in Figure 6.

It is also possible to design a dispersion measurement card and use a pair

10   of such cards for span-by-span measurement of dispersion. The card may be designed to perform measurements on all lines at the respective node. It has a size selected to fit into a respective rack, and a standard physical interface with the rack backplane. This is possible in an agile network which uses standard backplanes for all racks.

15   As indicated above, the measurements may be performed in this case off line or on line. In the case of off line measurements, the frequency is swiped along the respective band (C, L, or the like) in increments according to the ITU grid used in the network (100GHz, 50GHz, 25GHz). The dispersion data is used e.g. for selecting the fixed DCMs provided at the optical amplification sites, to

20   adjust the link dispersion to the target value for ULR. The measurements are further stored in tables for future use by the tunable DCMs provided at the switching nodes and by the routing and switching mechanism in the path selection process. A pair of cards may be moved from site to site if the cost of providing such cards at each node is of concern.

25   In the case that the measurement is performed on line, as discussed above, selection of wavelengths $\lambda 1$ and $\lambda 2$ takes into account the wavelengths that are currently in use on the respective link. However, as the measured data are recorded, and the wavelength configuration on the link changes, the measurement for all wavelengths will be obtained after a certain time.